


Unofficial Transcript

Thomas J. Watson

 This is **** NOT **** an official transcript.

Please Note:

- Courses "in progress" appear at the end of this report.
 - **For undergraduate activity,**
 - 1/3 unit activity is represented as 3.00 credit hours.
 - 1 Unit of activity is represented as 9.00 credit hours.
 - Other unit values are represented proportionately.
 - Information on minors and second majors is not displayed on this page.
 - The undergraduate GPA is not reflected on the Transcript.
- The '**Grade Point Average for Passed Courses**' appears on the Degree Audit web page.

[Transfer Credit](#) [Institution Credit](#) [Courses in Progress](#)

Transcript Data

STUDENT INFORMATION

Name : Thomas J. Watson

Birth Date: XXXXXXXXXX

Curriculum Information

Current Program

Major: Robotics Engineering

Major: Mechanical Engineering

This is NOT an Official Transcript

DEGREES AWARDED

Degree Sought: Bachelor of Science **Degree Date:**

Graduation Status: Pending completion of Requirements

Diploma Name : Thomas Jeffery Watson, Jr.

Curriculum Information

Primary Degree

Major: Robotics Engineering

Major: Mechanical Engineering

Interactive Qualifying Project: CDR grade=A : Social Issues of Wearable Augmented Reality Devices

Sufficiency: CDR grade=A : Spanish Language

TRANSFER CREDIT ACCEPTED BY INSTITUTION [-Top-](#)

xxx: Advanced Placement

Subject	Course	Title	Grade	Credit Hours	R
BB	1000	BIOLOGY ELECTIVE	L	3.000	
CH	1010	MOLECULARITY	L	3.000	
EN	1100	ENGLISH LITERATURE & COMP	L	3.000	
MA	1021	CALCULUS I	L	3.000	
MA	1022	CALCULUS II	L	3.000	
MA	2611	APPLIED STATISTICS I	L	3.000	
PH	1110	GENERAL PHYSICS-MECHANICS	L	3.000	
PH	1120	GEN. PHYSICS-ELEC-MAGNET	L	3.000	
SP	1523	ELEMENTARY SPANISH I	L	3.000	
			Attempt Hours	Passed Hours	Earned Hours
Current Term:			0.000	0.000	27.000

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Term: **Fall 2011**

Major: Robotics Engineering

Subject	Course	Level	Title	Grade	Credit Hours	Start and End Dates	R CEU Contact Hours
CS	1102	01	ACCELERTD INTRO TO PROGR DESGN	B	3.000		
MA	1023	01	CALCULUS III	A	3.000		
MA	1024	01	CALCULUS IV	A	3.000		
PE	1117	01	MISC (Ultimate Frisbee)	A	0.750		
PH	1111	01	PRINC OF PHYS-MECH	A	3.000		
PSY	1401	01	COGNITIVE PSYCHOLOGY	B	3.000		
RBE	1001	01	INTRODUCTION TO ROBOTICS	A	3.000		

Term Totals (Undergraduate)

	Attempt Hours	Passed Hours	Earned Hours
Current Term:	18.750	18.750	18.750
Cumulative:	18.750	18.750	18.750

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Term: **Spring 2012**

Major: Robotics Engineering

Subject	Course	Level	Title	Grade	Credit Hours	Start and End Dates	R CEU Contact Hours
ECE	2029	01	INTRO TO DIGITAL CIRCT DESIGN	A	3.000		

ES	2501	01	INTRO TO STATIC SYSTEMS	B	3.000
ETR	1100	01	ENGINEERING ENTREPRENEURSHIP	A	3.000
MA	2051	01	ORDINARY DIFFER. EQUATIONS	A	3.000
PE	1080	01	AQUATIC GAMES	A	0.750
SP	3521	01	ADVANCED SPANISH I	A	3.000
SP	3522	01	ADVANCED SPANISH II	A	3.000

Term Totals (Undergraduate)

	Attempt Hours	Passed Hours	Earned Hours
Current Term:	18.750	18.750	18.750
Cumulative:	37.500	37.500	37.500

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Term: Fall 2012

Major: Robotics Engineering

Subject	Course	Level	Title	Grade	Credit Hours	Start and End Dates	R CEU Contact Hours
ES	2001	01	INTRO TO MATERIAL SCIENCE	A	3.000		
ES	2502	01	STRESS ANALYSIS	A	3.000		
ES	2503	01	INTRO TO DYNAMIC SYSTEMS	A	3.000		
MA	2071	01	MATRICES&LINEAR ALGEBRA I	B	3.000		
RBE	2001	01	UNIFIED ROBOTICS I: ACTUATION	A	3.000		
RBE	2002	01	UNIFIED ROBOTICS II: SENSING	A	3.000		
SP	3530	01	SP FILM, MEDIA, AND CLTRL ISSU	B	3.000		

Term Totals (Undergraduate)

	Attempt Hours	Passed Hours	Earned Hours
Current Term:	22.500	21.000	21.000
Cumulative:	60.000	58.500	58.500

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Term: Spring 2013

Major: Robotics Engineering

Subject	Course	Level	Title	Grade	Credit Hours	Start and End Dates	R CEU Contact Hours
CS	2102	01	OBJECT-ORIENTED DESIGN CONCEPTS	B	3.000		
ECE	2049	01	EMBEDDED COMPUTNG IN ENG DESGN	A	3.000		
ES	3001	01	INTRO TO THERMODYNAMICS	B	3.000		
ES	3011	01	CONTROL ENGINEERING I	A	3.000		
GOV	2302	01	SCIENCE-TECHNOLOGY POLICY	A	3.000		
MA	2621	01	PROBABILITY FOR	A	3.000		

APPLICATIONS

SP 3526 01 COMPAR BUS ENVIRONMENTS B 3.000

Term Totals (Undergraduate)

	Attempt Hours	Passed Hours	Earned Hours
Current Term:	21.000	21.000	21.000
Cumulative:	81.000	79.500	79.500

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Term: Fall 2013

Major: Robotics Engineering

Subject	Course	Level	Title	Grade	Credit Hours	Start and End Dates	R CEU Contact Hours
CS	3733	01	SOFTWARE ENGINEERING	B	3.000		
ES	3004	01	FLUID MECHANICS	B	3.000		
IQP	RL1	01	SOCIAL ISSUES OF WEARABLE AR	B	3.000		
ME	3901	01	ENGINEERING EXPERIMENTATION	A	3.000		
RBE	4322	01	MDLNG & ANALY OF MECHATRN SYS	A	3.000		
SYS	579	01	SPECIAL TOPICS: MODEL- BASED DESIGN	A	3.000		

Term Totals (Undergraduate)

	Attempt Hours	Passed Hours	Earned Hours
Current Term:	18.750	18.000	18.000
Cumulative:	99.750	97.500	97.500

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Term: Spring 2014

Major: Robotics Engineering

Subject	Course	Level	Title	Grade	Credit Hours	Start and End Dates	R CEU Contact Hours
IQP	RL1	01	SOCIAL ISSUES OF WEARABLE AR	A	3.000		
IQP	RL1	01	SOCIAL ISSUES OF WEARABLE AR	A	3.000		
ISP	TP1	01	ROBOT MODELING IN GAZEBO	A	3.000		
RBE	3001	01	UNIFD ROBTICS III:MANIPULATION	A	3.000		
RBE	3002	01	UNIFIED ROBOTICS IV:NAVIGATION	A	3.000		
RBE	502	01	ROBOT CONTROL	A	4.500		

Term Totals (Undergraduate)

	Attempt Hours	Passed Hours	Earned Hours
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Current Term:	19.500	19.500	19.500
Cumulative:	119.250	117.000	117.000

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Term: Fall 2014**Major:** Robotics Engineering

Subject	Course	Level	Title	Grade	Credit Hours	Start and End Dates	R CEU Contact Hours
ES	3003	01	HEAT TRANSFER	A	3.000		
ME	5220	01	CNTRL OF LINEAR DYNAMCL SYSTEMS	A	3.000		
MQP	TP1	01	WALRUS ROVER MQP	A	3.000		
MQP	TP1	01	WALRUS ROVER MQP	A	4.500		
PE	1149	01	SAILING CLUB	A	0.750		
RBE	500	01	FOUNDATIONS OF ROBOTICS	A	4.500		
RBE	580	01	BIOMEDICAL ROBOTICS	A	3.000		

Term Totals (Undergraduate)

	Attempt Hours	Passed Hours	Earned Hours
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Current Term:	21.750	21.750	21.750
Cumulative:	141.000	138.750	138.750

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COURSES IN PROGRESS -Top-**Term: Spring 2015****Major:** Robotics Engineering

Subject	Course	Level	Title	Credit Hours	Start and End Dates
ME	5222	01	OPTIMAL CONTROL OF DYNAMICAL SYSTEMS	3.000	
MQP	TP1	01	WALRUS ROVER MQP	1.500	
MQP	TP1	01	WALRUS ROVER MQP	3.000	
PE	1016	01	SQUASH & RACQUETBALL	0.750	
RBE	501	01	ROBOT DYNAMICS	4.500	
RBE	595	01	SP TOP: MOTION PLANNING	4.500	

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RELEASE: 8.4.1

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